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Three-dimensional Bacterial Motions Near a Surface Investigated by Digital Holographic Microscopy: Effect of Surface Stiffness

Qingmei Peng, Xin Zhou, Zhi Wang, Qingyi Xie, Chunfeng Ma, Guangzhao Zhang, and Xiangjun Gong Langmuir, Just Accepted Manuscript • DOI: 10.1021/acs.langmuir.9b02103 • Publication Date (Web): 18 Aug 2019 Downloaded from pubs.acs.org on August 18, 2019

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*Correspondence should be addressed to X.G. (*E-mail*: <u>msxjgong@scut.edu.cn</u>). Abstract Surface stiffness plays a critical role in bacterial adhesion but the mechanism is unclear since the bacterial motion before adhesion is overlooked. Herein, the three-dimensional (3D) motions of *Escherichia coli* (E. coli) and *Pseudonomas*. sp nov 776 onto poly(dimethylsiloxane) (PDMS) surfaces with varying stiffness before adhering were monitored by digital holographic microscopy (DHM). As the Young's modulus (E) of PDMS surface decreases from 278.1 to 3.4 MPa, the adhered E. coli and *Pseudonomas*. sp decrease in number by 40.4 and 34.9 % respectively. Atomic force microscopy (AFM) measurements show that the adhesion force of bacteria to the surface declines with the decreased surface stiffness. In contrast, a non-tumbling mutant of adhered E. coli (HCB1414 with adaptive function being partially deficient) decreases much less (by 18.4 %). On the other hand, the tumble frequency (F_t) of E. coli HCB1 and flick frequency (F_f) of Pseudomonas sp. increase as the surface stiffness decreases, and the motion bias (B_{θ}) of *Pseudomonas* sp. also increases. These facts clearly indicate that the bacteria have adapted responses to the surface stiffness.

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RNA-sequencing (RNA-seq) reveals that the downregulated Cph2 and CsrA as well
 as the upregulated GcvA of swimming *E. coli* HCB1 in bulk near the softer surface
 promote the bacterial motility.

5 Keywords: surface stiffness, digital holographic microscopy, bacterial adhesion,
6 bacterial tracking, RNA-sequencing

8 Introduction

9 Bacterial adhesion is the primary step of biofilm formation, which is usually the start of marine biofouling,^{1,2} medical infection,³ and food contamination.^{4,5} It is recognized 10 that physicochemical properties of the surface, *i.e.*, surface hydrophobicity,⁶ charges,⁷ 11 topography^{8,9} and stiffness^{10,11} regulate bacterial adhesion. The effects of surface 12 stiffness on bacterial adhesion have drawn attentions in the past years. It was reported 13 that the adhesion of S. epidermidis was positively correlated with the surface stiffness 14 with E of 0.8 to 80 MPa by using polyelectrolyte multiplayer thin films as a model.¹² 15 For poly(ethylene glycol) dimethacrylate (PEGDMA) and agar hydrogel surface, less 16 E. coli and S. aureus adhere onto the softer surface (E rangs from 44 kPa to 6.5 17 MPa).¹³ Pseudoalteromonas sp. D41, a marine strain, also showed stronger adhesion 18 to rigid surfaces,¹⁴ which was explained by the so-called adapted response of bacteria 19 in a proteic study. In contrast, E. coli and P. aeruginosa exhibited weaker adhesion as 20

the PDMS surface stiffness increases.¹¹ Likewise, *Acanthamoeba castellanii* (*A.castellanii*), a eukaryotic protist, had an increased cell adhesion number with the
 decreasing *E* of PDMS substrate.¹⁵

The surface stiffness also affects bacterial motions during adhesion and biofilm growth. A two-dimensional cell tracking technique was utilized to observe the movement of E. coli attached on PDMS surfaces with E at 0.1 to 2.6 MPa.¹⁰ It revealed the flagellar motor of E. coli involves in an active response to surface stiffness. Such adaptive behavior was also observed in *P. aeruginosa*.¹⁶ The cells slingshot more on softer poly(N-isopropylacrylamide) (PNIPAM) surfaces at a shear-thinning condition, which facilitates their surface crawling. The growth rate of E. coli and P. aeruginosa biofilms, as well as the size and antibiotic susceptibility on PDMS increase as the surface stiffness decreases.¹¹ The growth of *E. coli* colonies is faster on a film with E = 30 kPa than the one with E = 150 kPa.¹⁷ Although many efforts have been made to correlate bacterial adhesion to surface stiffness, little attention was paid to how bacteria regulate their motions in response to the surface stiffness before adhesion.18,19

Attributed to the fact that the stiffness of the PDMS films prepared by spin coating is thickness dependent due to different shear stress during fabrication²⁰, we engineered PDMS surfaces with varying stiffness by tuning their thickness on glass coveslips. In this manner, the surface chemistry and topography change slightly and the bacterial responses to the surface stiffness can be solely examined. A home-made

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digital holographic microscopy (DHM) is utilized to track the planktonic bacteria (*E. coli* and a marine bacteria *Pseudomonas* sp.) before adhesion in 3D with time and spatial dependence. It has been applied to monitor the 3D dynamics of bacteria upon polymeric surfaces with different hydrophobicity⁶ and degradation rates.²¹ The adhesion forces between bacteria and surfaces were assessed by atomic force microscopy (AFM). Moreover, RNA sequencing (RNA-seq) of bacteria was applied for illuminating the mechanisms at a molecular level.

9 Experimental Section

Surface preparation. PDMS surface was prepared by SYLGARD184 Silicone Elastomer Kit (Dow Corning). The ratio (w/w) of the prepolymer to curing agent was fixed at 10:1. The concentration of PDMS to tetrahydrofuran (THF, Sinopharm) were 5, 15 and 25 % (w/v). The coverslips (22×22 mm, Fisher Scientific) were cleaned by immersion in a fresh piranha solution (H_2O_2/H_2SO_4 , 3:7 v/v; 90 °C) for 2 h, then sonication in deionized water (DI water) and ethanol for 5 min, respectively, and dried with nitrogen before use.

PDMS films with thickness of 0.4, 0.8, and 2.0 μ m (Figure S1) were prepared on the cleaned coverslips by spin-coating 200 μ L of 5, 15 and 25 % PDMS/THF solutions through a spin-coater (KW-4, CHEMAT) at 3,000 rpm in air, respectively. The coated coverslips were cured at 80 °C for 2 h, and incubated at room temperature

for 24 h to be fully cross-linked. The cured surfaces were sterilized by washing with
 ethanol and dried with nitrogen gas.

Surface characterization. AFM (XE-100, Park Systems) was utilized to measure the thickness of the PDMS coatings. The measurement was conducted with rectangular silicon cantilever (NCHR, spring constant 42 N/m, Nanosensors) in a tapping mode. The PDMS surfaces were scraped with a blade to expose the substrate, the probe was then allowed to slowly approach and scan imaging. With the relative height between the PDMS film and substrate in the surface topography, the thickness of the coatings was obtained.²²

Young's modulus (*E*) determined by force-distance curves executed with AFM
was used to quantify the stiffness of the surface.⁶ The recorded force-indentation
curves were fit to the Hertzian contact model at the linear elasticity region (Figure S2). *E* of the surfaces was obtained by the following equation:²³

$$F = \frac{E}{1 - \nu^2} \frac{\tan \alpha}{\sqrt{2}} \delta^2 \tag{1}$$

where v is the Poisson's ratio of PDMS surface which is assumed to be $0.5.^{24} \alpha$ is the four-sided pyramidal face angle of cantilever tip (22°). The indentation depth $\delta = d_p - d_f$, in which d_p is the piezo displacement of AFM, and d_f is the deflection of the cantilever free end. *F* is the applied force obtained from the force curve.

Surface roughness (R_q) was measured with rectangular silicon cantilever in the

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tapping mode. All AFM measurements were conducted in air at 25 °C with at least three times on different positions. Surface potential (ζ) was acquired in 10 mM NaCl solution by using a DelsaNano C particle and zeta Potential Analyzer (Beckman Coulter). Theta optical tensiometer (T200-Auto1B, Biolin Scientific) was performed to obtain the static water contact angle (WCA) of these surfaces. The elemental composition was analyzed by X-ray photoelectron spectrometer (Axis uHru DCD, Krates, see Figure S3). Surface characterization methods mentioned above were repeated for three times.

Bacterial strain and culture. A wild-type Escherichia coli (HCB1), a smooth-swimming mutant (HCB1414 AcheY AcheZ, non-tumbling motion), and a marine bacteria Pseudomonas sp. nov 776 isolated from marine subtidal biofilms were used in this study. E. coli and Pseudomonas sp. cells were streaked on luria broth (LB) and marine agar (MA) plates, respectively. A monoclonal colony was inoculated into a fresh growth medium. After growing up to mid-log phase (OD_{600} = 0.4), the bacterial suspension was diluted into a motility buffer (MB) with the ratio of 1:10 (v/v), more details were described elsewhere.²¹

Before DHM observation, the suspension was injected into a chamber (16 mm of
length, 1 mm of width, 100 µm of height) consisting of a PDMS microfluidic chip
(Suzhou Wenhao Microfluidic Tech. Co., Ltd., China) and a PDMS coated coverslip.
The chip was treated in a plasma cleaner (PDC-002, Harrick Plasma) for 10 min
before sticking to the coated substrates. Motility buffer was continuously injected into

the channel for 15 min before observation. Since the experiment was conducted under a static condition, the chip would be sealed after the channel was filled with the suspension.

Measurements of bacterial adhesion force. AFM was performed to measure the adhesion force between a colloidal probe covered with bacteria and the surface. A 23 µm diameter SiO₂ microsphere (Suzhou Nano-Micro Technology Co., Ltd, China) was attached to the silicon nitride tip on the end of the cantilever to make a colloidal probe. The colloidal probe was treated with plasma for 10 min and disposed in a 1% (w/v) poly(ethyleneimine) (PEI, $M_w = 1800$, Aladdin) for 2.5 h, then cleaned with DI water. The treatment of PEI enabled the bacteria to be firmly adhered on SiO₂ microsphere. Bacteria were prepared by centrifugating (2000 g, 5 min) the mid-exponential phase bacterial suspension for three times, dispersed into a 3% (w/v) glutaraldehyde solution at 4 °C for 2.5 h, and cleaned with MB for two times.^{6,25} 10 μ L of the treated bacterial suspension was added onto a cleaned silicon wafer. Afterwards, the colloidal probe was brought proximity to the drop and immersed in it for 15 min to enhance the coverage of bacteria. The interactions between bacteria and the surface in MB were measured immediately. The surface force separation curves were obtained under a contact mode. The adhesion force corresponds to the maximum tip deflection upon the retraction of the cantilever.²⁶ Each attraction force (γ) obtained from the force statistics was measured at least three times (12 different positions).

21 Digital holographic microscopy (DHM). DHM for 3D bacterial tracking is based on

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1	an in-line configuration integrated with an inverted microscope (IX-83, Olympus,
2	Japan). ^{27,28} A 40× microscope objective (NA = 0.6, LUCPLFLN40×, Olympus) was
3	utilized. The bacterial suspension was illuminated uniformly by a collimated
4	light-emitting diode (LED, $\lambda = 455$ nm, Thorlabs, US), and part of the incident light
5	was scattered by the suspension. Real-time holograms of 1024×1024 pixels formed
6	by the interference of the scattered and unscattered incident light were recorded using
7	a sCMOS camera (Zyla-5.5-CL3, 6.5 μ m/pixel, Andor Technology, UK) at 20
8	frames/s. More details were introduced elsewhere. ^{6,21} DHM experiments for each
9	surface with the specific stiffness were repeated for four times and performed at
10	25 °C. Each hologram would be subtracted by a background image which was
11	generated by averaging all images recorded in 2 min to aviod the stationary noise.
12	Bacterial adhesion is quantified as the number of bacteira adhered onto the
13	background image (N_b). The independent 3D coordinates of each bacterium was based
14	on Rayleigh-Sommerfeld proporgation ^{27,29} and further connected to continuous
15	trajectories by a home-made programme. The bottom surface $(z = 0)$ was set as the
16	location of bacteria with the shortest reconstructed distance to the focal plane, then a
17	relative height (z) of bacteria in different positions could be obtained.

Data Processing. Mean square displacement (*MSD*) was used to describe the motility of bacteria.²¹ The *MSD* - Δt curve was fit by the equation $MSD(\Delta t) = D(\Delta t)^{\nu}$, and the index v was obtained from the first 10 % continuous points of each *MSD* - Δt curve. The motion of the observed bacteria was classified into active and subdiffusive by the

power index v. $v \ge 1$ represents an active motion, while v < 1 corresponds to a subdiffusive motion. N_{sub} refers to the number of subdiffusive motion of bacteria upon surfaces ($0 < z < 10 \mu m$).

3D orientation, motion patterns, density distribution n(z), and collision analysis were all derived from the 3D trajectories of the bacteria with the active motion. The bacterial orientation was defined as the angle (θ) between the surface normal and swimming direction of bacteria. When $\theta > 90^{\circ}$ (θ_{down}), the bacteria swim toward the surface but away from the surface at $\theta < 90^{\circ}$ (θ_{up}). E. coli HCB1 cells swim by rotating a bundle of flagella as the flagellar motors turn in a counterclockwise direction.³⁰ A tumble defined as an obvious change in the direction (over 75 degree) of trajectory is caused by the dispersal of the flagellar bundle or clockwise rotation of the motors.³¹ Pseudomonas sp. swimming by rotating a single polar fagellum, moves in a three-step swimming pattern containing forward, reverse and flick.^{30,32} The flagellum will flick and choose a new direction randomly.³³ The critical angles of the flick and reverse event are 70 and 110 degree in our analysis. Tumble frequency (F_t) and flick frequency (F_f) were applied to describe the tumble and flick occurrence of bacteria per second. Besides, the distance range from the surface where 50 % bacteria cells locate in was described as D_r . An increased D_r indicates a dispersed distribution. All results were compared using a Student's t test (between the cases of surface with E = 278.1 MPa and the other softer surfaces, respectively) or one-way ANOVA. Significance was assumed when p < 0.05.

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1	RNA sequencing (RNA-seq). E. coli HCB1 was used for RNA extraction. E. coli
2	was collected from the suspensions upon surfaces with $E = 278.1$ (S _{stiff}) and 3.4 MPa
3	(S_{soft}) , respectively, and with an independent replicate. The samples were then
4	centrifugated at 4 °C, 8000 rpm for 5 min. Removed the supernatant and stored at -80
5	°C. Trizol method was performed to extract the total RNA of each sample. RNA
6	quality was detected by agarose gel electrophoresis. Agilent 2100 and Agilent 2100
7	RNA 6000 Pico kit were applied to identify the purity and concentration of the
8	RNA-seq sequencing samples. Oligotex mRNA Kits Midi were utilized to enrich the
9	mRNA. The small RNA libraries were sequenced on the Illumina sequencing
10	platform by Genedenovo Biotechnology Co., Ltd (Guangzhou, China). The
11	sequencing depth of samples was 1 G. After the sequencing run, paired-end
12	nucleotide reads were further filtered to obtain high quality clean reads and mapped to
13	the reference genomic sequence of <i>E. coli</i> K-12 MG1655 (NCBI: txid511145). ³⁴ The
14	unique mapped ratios of samples to reference genes are distributed between 93.85 to
15	95.64%. The reproducibility of the two replicates could be reflected by the Pearson
16	correlation shown in Figure S4. The coefficients of S_{stiff} and S_{soft} are 0.98 and 0.87,
17	respectively, indicating a relatively good biological repeatability. The filter was set as
18	p < 0.05, fold change (FC) >1.5 to analyze the differential expression of genes.

20 Results and Discussion

1	PDMS is a viscoelastic material. Figure S5 implies the dynamic stiffness (k_d) and the
2	loss modulus (G''), which indicate the surface viscoelasticity correlated negatively
3	with the thickness of the PDMS films. For better comparison with previous works, the
4	Young's modulus (E) was used to describe the stiffness of the PDMS surfaces.
5	Accordingly, for PDMS coatings with thickness of 0.4, 0.8, and 2 μ m, E inversely
6	related to the thickness are 278.1 \pm 147.6, 35.0 \pm 13.0, and 3.4 \pm 0.4 MPa,
7	respectively (Figure 1a). E of the substrate (glass coverslip) is dozens to hundreds
8	GPa, ³⁵ which is much higher than that of PDMS. As a result, the increased modulus
9	for a reduced thickness (less than 2 μ m) is understandable because the influence from
10	the substrate becomes significant. However, the thickness does not make difference in
11	surface roughness (R_q), surface potential (ζ) and static water contact angle (CA)
12	between the surfaces (Figure 1b, 1c and 1d). The surface can be treated as uncharged
13	since they have a potential of \pm 10 mV, ^{36,37} and the effect of electrostatic force can be
14	neglected. The surface composition analysis in Figure S3 further indicates the little
15	distinction of elemental mass concentration between surfaces. Thus, surfaces with
16	varying stiffness and consistent surface chemistry were obtained by tuning the film
17	thickness.



Figure 1. Characterization of PDMS coatings. (a) Young's modulus (E) of the coatings as a
function of thickness. (b) Surface roughness (R_q). (c) Surface potential (ξ). (d) Water contact angle
(CA).

Surface adhesion of *E. coli* HCB1 and *Pseudomonas* sp. was assessed (Figure 2a). For HCB1, compared with the adhered bacteria ($N_b = 1.77 \times 10^5 \cdot \text{cm}^{-2}$) on a glass surface, N_b obviously decreases for all the PDMS surfaces which is softer. Similarly, Figure 2a showed N_b decreases by 40.4 and 34.9 % for *E. coli* HCB1 and *Pseudomonas* sp. as the Young's modulus decreases from 278.1 to 3.4 MPa, indicating the bacteria prefer to adhere onto the stiffer surface. Similar phenomena

were observed for E. coli and S. aureus on the surfaces of synthetic polymer and biopolymer hydrogels,¹³ where the stiffness was regulated by the component concentration. Bacteria tend to exhibit subdiffusive motion before irreversible adhesion, which is mediated by the flagella or pili.^{38,39} Therefore, N_{sub} , defined as the number of bacteria presenting a subdiffusive motion near the surface ($0 \le z \le 10 \ \mu m$) was calculated. As shown in Figure 2b, N_{sub} of E. coli HCB1 and Pseudomonas sp. significantly decreases as the surface stiffness decreases (p < 0.05, one-way ANOVA). This agrees with the reduced N_b for the softer surface in Figure 2a.



Figure 2. (a) Adhesion number (N_b) and (b) subdiffusive (v < 1) population density (N_{sub}) ($0 < z < 10 \mu m$) of *E. coli* HCB1 and *Pseudomonas* sp. upon PDMS surfaces with varying stiffness. (*) and (**) denotes significant difference at p < 0.05 and 0.01, compared to the results for the surface

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with E = 278.1 MPa and determined by *t* test.

3	The reduced $N_{\rm b}$ can be explained by adhesion force (γ) between bacteria and
4	surface measured by AFM (Figure 3). As the Young's modulus decreases from 278.1
5	to 3.4 MPa, γ for <i>E. coli</i> HCB1 significantly decreases from ~ 800 to ~ 170 nN while
6	γ for Pseudomonas sp. decreases from ~ 2200 to ~ 300 nN. It might be the
7	consequence of the decreased viscosity as the surface becomes softer (shown in
8	Figure S5b). Accordingly, when bacteria collide with the surface with a force of 2.1
9	pN, ⁶ the surface with $E = 3.4$ MPa has a deformation of 0.62 nm ² , much more than
10	that 7.6 \times 10 ⁻³ nm ² of the surface with $E = 278.1$ MPa. The softer surface with larger
11	deformation is more difficult for bacteria to land and adhere on, which leads to a
12	reduced adhesion force, and thus significantly decreasing $N_{\rm b}$.



6 We also examined the 3D orientation (θ) of actively swimming bacteria. The 7 motion bias (B_{θ}) defined as the ratio of θ_{up} to θ_{down} was used to describe the motion 8 tendency of bacteria. $B_{\theta} = 1$ represents the uniformly orientation of bacteria, while 9 $B_{\theta} > 1$ and < 1 indicates bacteria tend to move away from the surface and accumulate 10 on the surface. Figure 4a shows B_{θ} of *E. coli* HCB1 makes small difference (p = 0.09, 11 one-way ANOVA) among the surfaces with varying stiffness. In contrast, B_{θ} of

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Pseudomonas sp. increases from 0.95 to 1.1 as the surface becomes softer. The facts indicate *Pseudomonas* sp. cells tend to swim away from the surface with E = 3.4 MPa but accumulate on the surface with E = 278.1 MPa. This is in accordance with the density distribution (heatmaps) of Pseudomonas sp. shown in Figure 4b and 4c, where the bacteria in 0 < z < 5 µm upon surface with E = 278.1 MPa is much denser than the 3.4 MPa one.



Figure 4. Orientation of bacteria upon PDMS surfaces with different stiffness. (a) Motion bias (B_{θ}) of actively swimming *E.coli* HCB1 and *Pseudomonas* sp. upon PDMS surfaces. $(B_{\theta} =$ $\theta_{\rm un}/\theta_{\rm down}$, active bacteria in the range of 0 to 5 µm). Density distribution (heatmaps) of instantaneous 3D velocities and distances (z = 0 to 30 µm) from the (b) 278.1 and (c) 3.4 MPa surfaces for *Pseudomonas* sp. Color bars represent the relative density of data points with a logarithmic scale. (*) denotes significant difference at p < 0.05, compared to the results for the surface with E = 278.1 MPa group and determined by t test.

Figure 5a and 5b show the typical swimming trajectories of E. coli HCB1 and *Pseudomonas* sp, respectively. Unlike the molecules or polymers undergo diffusion or

1	subdiffusion determined by the hydrodynamic interactions near a surface, ⁴⁰ bacteria
2	swim actively and present many unique motion features. The swimming pattern of the
3	peritrichous bacteria like E. coli HCB1 is divided into linear forward swimming (run)
4	and abrupt changes in direction (tumble), which is highly associated with the
5	chemotactic behavior of bacteria. ⁴¹ F_t of <i>E. coli</i> HCB1 increases from 1.21 to 1.49
6	when the Young's modulus decreases from 278.1 to 3.4 MPa (Figure 5c), and it is
7	significantly larger than F_t of HCB1 upon the glass surface reported in our former
8	work. ⁶ The polarly uni-flagellated marine bacteria <i>Pseudomonas</i> sp. execute a cyclic
9	swimming pattern (forward, reverse, and flick). It is known that flick event is related
10	to tactical behaviors of bacteria in response to the environment. ^{32,33} As shown in
11	Figure 5d, $F_{\rm f}$ is significantly raised from 1.06 to 1.44. This tendency agrees with the
12	similiar bacterial orientation of <i>Pseudomonas</i> sp. near different surfaces (Figure 4a).
13	Therefore, the increase of the tumble and flick events are related to the adapted
14	response of bacteria to the surfaces with different stiffness. We will come back to this
15	later.



Figure 5. Typical trajectories of (a) *E. coli* HCB1 and (b) *Pseudomonas* sp. Tumble frequency (F_t) and flick frequency (F_f) of (c) *E. coli* HCB1 and (d) *Pseudomonas* sp., respectively. (*) denotes significant difference at p < 0.05, compared to the results for the surface with E = 278.1 MPa group and determined by *t* test.

As discussed above, the decreased N_b of bacteria upon the softer surface results from interactions between bacteria and surface with varying stiffness, *i.e.*, adhesion force, and adapted responses of bacteria to the surroundings with different stiffness, *i.e.*, tumble or flick. Thus, the adhesion of a chemotaxis deficient mutant of *E. coli*, *i.e.*, non-tumbling HCB1414 was examined to evaluate their contribution. Figure S6 and S7 show that N_b decreases by 18.4 % as the Young's modulus decreases from

1 278.1 to 3.4 MPa. Since HCB1414 does not exhibit the typical adapted response 2 (tumble), the reduction in N_b should be mainly attributed to the weaker 3 bacteria-surface interactions as surface stiffness decreases. With HCB1414 as the 4 reference, the contribution from the bacteria-surface interactions for HCB1 is 5 estimated to be 45.5 %.

The typical density distributions of HCB1414 and HCB1 actively swimming near the surface with E = 278.1 MPa are shown in Figure 6a. Bacteria swim and accumulate in the vicinity of surfaces before adhesion because of the hydrodynamic interaction.^{42,43} HCB1414 without the motion of tumble tends to be more concentrated upon surfaces. This is consistent with the result that the total n(z) at near-surface region ($0 < z < 3 \mu m$) of HCB1414 is about 0.5, obviously larger than that of HCB1 (0.2), indicating that the near-surface density distribution increases as E. coli lacking the adapted response (tumble). Meanwhile, as shown in Figure 6b, D_r of HCB1414 slightly increases from 2.87 to 4.89 µm, arising from hydrodynamic interactions upon the surfaces with E = 278.1 to 3.4 MPa. For HCB1, D_r increases from 14.22 to 19.22 μ m, in which bacteria-surface interactions contributes by 40.4 % obtained from the increment of D_r for HCB1414 to that for HCB1, and the adapted responses by 59.6 %. Generally, they are consistent with the results about $N_{\rm b}$.



Figure 6. (a) Density distribution (n(z)) of bacteria upon the PDMS surface (E = 278.1 MPa). (b)
The distribution range (D_r) of 0 - 50 % HCB1414 and HCB1 cells closer to the surface. (*)
denotes significant difference at p < 0.05, compared to the results for the surface with E = 278.1
MPa group and determined by t test.

Finally, RNA-seq was employed to explore the molecular-level mechanism of bacterial behaviors upon surfaces with different stiffness. We collected E. coli HCB1 in bulk instead of the attached cells uopn surfaces with E = 278.1 (S_{stiff}) and 3.4 MPa (S_{soft}) to confirm the adapted responses of swimming bacteria to surface stiffness. There are 189 differential expression genes, 82 upregulated and 107 downregulated (Figure S8). Note that a GGDEF domain-containing protein Cph2 which can indirect regulate the level of the second messenger cyclic dimeric guanosine monophosphate $(c-di-GMP)^{44}$ is downregulation in S_{soft} compared to S_{stiff} (Figure 7a). C-di-GMP plays an important role in sensing environmental cues.45,46 The model of c-di-GMP molecular regulation module is shown in Figure S9. The increased level of

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intracellular c-di-GMP will inhibit the bacterial motility and promote biofilm formation.⁴⁷ Meanwhile, the c-di-GMP level is connected with the surface stiffness.⁴⁸ Figure S10 shows the 3D velocity (V_{3D}) increment of bacteria from z = 10 to 1 μ m. The increment changes from -0.14 to 17.04 %, -1.88 to 7.59 % of E. coli HCB1 and *Pseudomonas* sp. upon the surfaces with E = 278.1 to 3.4 MPa. Clearly, a higher motility of bacteria is observed when surface becomes softer, which is in accordance with the phenomenon in Figure 5. As a result, the decrease of the GGDEF domain protein reduces the intracellular c-di-GMP level but improves the motility of bacteria and thus decreases $N_{\rm b}$ on the softer surface.

Besides, in the process of KEGG pathway enrichment, downregulated CsrA and upregulated GcvA of S_{soft} in the pathway of biofilm formation is correlated to bacterial adhesion (Figure 7a). As shown in Figure 7b, the decrease of CsrA could lower the biosynthesis of glycogen and poly(*N*-acetyl-glucosamine) (PGA), which is related to exopolysaccharides (EPS). The adhesion of bacteria to a surface can be enhanced by EPS.^{49,50} EPS produced by bacteria reduces as the surface becomes softer. This can account for the decreased adhesion force in Figure 3. Meanwhile, the upregulated GcvA shows an indirect effect on the inhibition of biofilm formation, thus decreasing $N_{\rm b}$ on the softer surface.



Figure 7. (a) The difference of Cph2, CsrA, and GcvA expression level in S_{soft} compared to S_{stiff}.
FC refers to fold change. (b) Partial pathway for biofilm formation. (1) expression (2) inhibition (3)
change of state (4) indirect effect. (Green and red boxes mean downregulated and upregulated
genes, respectively.)

7 Conclusion

The 3D motions of E. coli and Pseudomonas sp. upon PDMS surfaces with different stiffness were tracked by DHM. For E. coli wild strain HCB1 and marine bacteria *Pseudonomas* sp., the adhering and subdiffusively swimming populations significantly decrease as the surface becomes softer. Adhesion number of a non-tumbling E. coli HCB1414 which is a mutant with adaptive function partially deficient decreases much less upon the softer surface than the above two strains. AFM measurements indicate the reduction of the adhesion force of bacteria to the surface as the surface stiffness decreases. From DHM measurements, adaptive behaviors, *i.e.*, tumble motions for HCB1 and flick motions for Pseudomonas sp. become more frequent as the surface stiffness decreases, while the motion bias (B_{θ}) of *Pseudomonas*

sp. increases. RNA-seq of HCB1 reveals that the downregulation of Cph2 enhances

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2 the bacterial motility, while the downregulation of CsrA and upregulation of GcvA inhibit the bacterial adhesion. These results imply surface stiffness modulates 3 bacterial adhesion through physical interaction (40%) and bacterial adaptive responses 4 (60%). 5 6 **ASSOCIATED CONTENT** 7 **Supporting Information** 8 9 Thickness of PDMS coatings; Fitting process of Young's modulus by Hertzian model; XPS scan spectra and elemental mass concentration; Correlation Heatmap; k_d and G''10 of the PDMS surface; N_b of E. coli HCB1414; P_d of bacteria; Statistics of differential 11 expression genes; A model of c-di-GMP molecular regulation module; Variable of 12 13 $V_{\rm 3D}$ from z = 10 to 1µm.

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15 AUTHOR INFORMATION

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- 18 Notes

1 The authors declare no competing financial interests.

ACKNOWLEDGEMENTS

The financial support of National Natural Science Foundation of China (21574046,
51573061), the National Natural Science Foundation of Guangdong Province
(2019B030301003) and the Fundamental Research Funds for the Central Universities
is acknowledged.

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